Advancing Sampling Techniques: Multivariate Ratio Estimation for Variance Vector in Two-Phase Sampling

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Abstract

The problem of variance vector estimation using multi-auxiliary variables is not quite often considered in the literature. In the present study, we propose a multivariate ratio estimation approach for estimating a vector of variances in two-phase sampling using a vector of l variables, following the situation if the desired parameters are available only for some of the auxiliary variables. Some special cases of the proposed generalized multivariate variance estimator have also been discussed. Expressions of the bias, and generalized variance has been derived. With the help of real-life data, the applicability of the proposed multivariate variance estimator is more efficient than the modified versions of multivariate variance estimators. A simulation study has also been carried out to show that the proposed estimator surpasses the modified version of multivariate estimators.

Keywords: variance-covariance matrix; two-phase sampling; bias; ratio estimator; multi-auxiliary variables; simulation

1. Introduction

We ruminate a finite population $\left[\Omega = \{\Omega_1, \Omega_2, ..., \Omega_N\}\right]$. Let Y_j be the variable under study where j = 1, 2, ..., m and X_j be the auxiliary variable where k = 1, 2, ..., l. Let $\overline{Y_j}$ and $\overline{X_k}$ be the population means and $S_{y_j}^2$ and $S_{x_k}^2$ be the population variances of the study and auxiliary variable respectively. Further, let $C_{x_k}^2$, $C_{y_j}^2$ be the coefficients of disparity and $\rho_{y_j x_k}$ indicates the correlation coefficient between study and ancillary variables. We are considering two-phase sampling design; where the first-phase sample of size n_1 is particular from the population N units and the second-phase sample of n_2 units are selected from $n_1(n_2 \subset n_1)$. Now an assumption is made that only l_1 auxiliary variables are available with their known population means and variances while l_2 represents the unknown auxiliary information.

Let $s_{y_{(2)j}}^2 = S_{y_j}^2 (1 + \varepsilon_{y_{(2)j}})$, $s_{x_{(2)k}}^2 = S_{x_k}^2 (1 + \varepsilon_{x_{(2)k}})$ and $\overline{x}_{(1)k} = \overline{X}_k (1 + \overline{e}_{x_{(1)k}})$ defined the relative errors and $\varepsilon_{y_{(2)j}}$, $\varepsilon_{x_{(2)k}}$ and $\overline{e}_{x_{(1)k}}$ be the sampling errors. To understand the properties of an estimator, some necessary expectations are shown by,

$$E\left(\varepsilon_{x_{(1)k}}\right) = E\left(\varepsilon_{x_{(2)k}}\right) = 0,$$

$$E\left(\varepsilon_{y_{(2)j}}\right) = 0, \ E\left(\overline{e}_{x_{(1)k}}\right) = E\left(\overline{e}_{x_{(2)k}}\right) = 0, \ E_{2}\left(\varepsilon_{y_{(2)j}}^{2}\right) = \gamma_{2}A_{y} = \gamma_{2}\left[\beta_{2}(y) - 1\right], \ E_{2}\left(\varepsilon_{x_{(2)k}}^{2}\right) = \gamma_{2}A_{x} = \gamma_{2}\left[\beta_{2}(x) - 1\right],$$

$$E\left(\varepsilon_{y_{(2)}}\varepsilon_{x_{(1)}}\right) = \gamma_{1}A_{yx} = \gamma_{1}\left[\varphi_{220} - 1\right], \ E_{1}E_{2}\left(\overline{e}_{x_{(1)k}}\varepsilon_{y_{(2)}}\right) = \gamma_{1}A_{yx_{d}} = \gamma_{1}\varphi_{210}C_{x_{k}},$$

$$E_{1}\left(\overline{e}_{x_{(1)k}}^{2}\right) = \gamma_{1}A_{x_{d}} = \gamma_{1}C_{x_{k}}^{2}, \ E_{1}\left(\overline{e}_{x_{(2)k}}^{2}\right) = \gamma_{1}A_{x_{d_{1}}} = \gamma_{1}C_{x_{k}}^{2}, \ E_{1}(\overline{e}_{x_{(1)k}}\overline{e}_{x_{(1)h}}) = \gamma_{1}A_{x_{dk}x_{h}} = \gamma_{1}C_{x_{k}}C_{x_{h}}\rho_{x_{k}x_{h}},$$

where $k \neq h$

where E_1 and E_2 denotes the potentials over first and second phase and $\beta_2(y)$, $\beta_2(x)$ are Kurtosis of the study and auxiliary variable respectively.

$$\begin{split} \varphi_{p_1...p_m q_1...q_l} &= \frac{\mu_{p_1...p_m q_1...q_l}}{\mu_{200}^{p_1...p_m/2} \mu_{020}^{q_1...q_l/2}} \\ \varphi_{p_1...p_m q_1...q_l} &= \frac{1}{N} \sum_{i=1}^N (Y_{i1} - \overline{Y_1})^{p_1} (Y_{i2} - \overline{Y_2})^{p_2} \dots (Y_{ij} - \overline{Y_1})^{p_m} (X_{i1} - \overline{X_1})^{q_1} (X_{i2} - \overline{X_2})^{q_2} \dots (X_{ik} - \overline{X_k})^{q_l} \end{split}$$

We use the following results using simple random sampling without replacement (SRSWOR) for the derivation of bias and variance-covariance (Var-Cov) matrices under two-phase sampling in multivariate situations,

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$$\begin{split} \Delta_{y} &= \begin{bmatrix} \varepsilon_{y_{(2)1}} & \varepsilon_{y_{(2)2}} & . & \varepsilon_{y_{(2)m}} \end{bmatrix}, \\ \Delta_{x} &= \begin{bmatrix} \varepsilon_{x_{(1)1}} & \varepsilon_{x_{(1)2}} & . & \varepsilon_{x_{(1)/1}} \end{bmatrix}, \Delta_{x_{1}} = \begin{bmatrix} \varepsilon_{x_{(2)1}} & \varepsilon_{x_{(2)2}} & . & \varepsilon_{x_{(2)/2}} \end{bmatrix}, \\ \overline{D}_{x} &= \begin{bmatrix} e_{x_{(1)1}} & e_{x_{(1)2}} & . & e_{x_{(1)/1}} \end{bmatrix}, \overline{D}_{x_{1}} = \begin{bmatrix} e_{x_{(2)1}} & e_{x_{(2)2}} & . & e_{x_{(2)/2}} \end{bmatrix}, \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x}' \Delta_{x} \end{pmatrix} = \gamma_{1} \sum_{x_{(1)\times 1}}, E_{1}E_{2/1} \begin{pmatrix} \Delta_{y}' \Delta_{y} \end{pmatrix} = \gamma_{2} \sum_{y_{(m\times m)}}, E_{1}E_{2/1} \begin{pmatrix} \Delta_{x}' \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{xy_{(1)\times m}}, \\ E_{1}E_{2/1} \begin{pmatrix} \overline{D}_{x}' \overline{D}_{x} \end{pmatrix} = \gamma_{1} \sum_{x_{d_{1}\times h}} E_{1}E_{2/1} \begin{pmatrix} \Delta_{y}' \overline{D}_{x} \end{pmatrix} = \gamma_{1} \sum_{yx_{d_{1}\times h_{1}}} , E_{1}E_{2/1} \begin{pmatrix} \overline{D}_{x}' \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{d_{1}(1)\times m}}, \\ E_{1}E_{2/1} \begin{pmatrix} \overline{D}_{x'} \overline{D}_{x} \end{pmatrix} = (\gamma_{2} - \gamma_{1}) \sum_{x_{d_{1}(1)\times d_{2}}}, E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{x_{1}} \end{pmatrix} = (\gamma_{2} - \gamma_{1}) \sum_{x_{1}(1)\times d_{2}}, \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} E_{1} & E_{1} & E_{1} & E_{1} & E_{1} & E_{1} & E_{1} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m}} \\ E_{1}E_{2/1} \begin{pmatrix} \Delta_{x'} \Delta_{y} \end{pmatrix} = \gamma_{1} \sum_{x_{1}y_{(1)\times m$$

 $\gamma_1 = \frac{1}{n_1}$ and $\gamma_2 = \frac{1}{n_2}$, Σ represents the variance-covariance matrix.

Ahmed (2000) proposed the two estimators for assessing finite population variance using multivariate assisting variables when assisting variables are known and found that their estimators are more efficient than Isaki (1983). Abu-Dayyehand Ahmed (2002) proposed the ratio and regression estimators when assisting variables are not known for the population but known for the large samples with moderate cost. They proposed the variance estimator using two auxiliary variables under two-phase sampling. Kadilar and Cingi (2007) also suggested the regression estimator using an auxiliary variable and exposed that their estimator is more efficient than Isaki's (1983) ratio and regression estimator under assured situations. There are some other vital studies in the fiction such as Kim and Sitter (2003) Singh et al. (2003), Singh et al. (2010), Singh and Solanki (2013), Olufadi and kadilar (2014), Asghar et al. (2014), Singh and Singh (2015), Yadav et al. (2015), Singh and Pal (2016), Sanaullah et al. (2016), and recently Ismail et al. (2018), Abid et al. (2019), Naz et al. (2020), Zaman et al. (2021), Daraz et al. (2021) and Niaz et al. (2022) developed the ratio estimators for estimating population variance. Further, Cekim and Kadilar (2020) proposed the In-type regression estimators for variance estimation under SRS and Haq et al. (2021) worked on the variance estimators under stratified sampling.

In this paper, we have considered the multivariate situation when some of the assisting variables are known, and the others are unknown, and we have adopted the two-phase sampling for estimating population variance. The goal of this study is to show how we can deal with the multiple situations using known and unknown auxiliary variables for estimating the variance vector. The arrangement of the paper is as follows, in Section 2, we modify some existing estimators into multivariate cases and find their Var-Cov matrices. The bias and Var-Cov matrix of multivariate ratio type estimator is given in Section 3. A real-life example has been taken to exhibit the routine of our suggested estimator in Section 4. Section 5 is based on the simulation studies and lastly, conclusions are presented in Section 6.

2. Modify form of some existing estimators

An unbiased estimator of population variance is sample variance i.e., $t_0 = s_y^2$, We modify it in multivariate case using multi-

auxiliary variables as
$$t_{0d} = \begin{bmatrix} t_{0d1} & t_{0d2} \cdots & t_{0dj} \cdots & t_{0dm} \end{bmatrix}$$
,
 $t_{0dj} = s_{y_{(2)j}}^2$, $j = 1, 2, ..., m$, (1)

and variance of unbiased estimator is $Var(t_0)$,

Isaki (1983) suggested ratio estimator for estimating population variance is t_r .

Modify it in multivariate form as $t_r = \begin{bmatrix} t_{r1} & t_{r2} \cdots & t_{rj} \cdots & t_{rm} \end{bmatrix}$,

$$t_{rj} = s_{y_{(2)j}}^2 \prod_{k=1}^{l_1} \left(\frac{S_{x_{(1)k}}^2}{s_{x_{(1)k}}^2} \right) \prod_{k=l_1+1}^{l_1+l_2=l} \left(\frac{s_{x_{(1)k}}^2}{s_{x_{(2)k}}^2} \right), \quad j = 1, 2, ..., m, \quad k = 1, 2, ..., l,$$
(2)

and its Var-Cov matrix is given,

$$\Sigma_{tr_{(m\times m)}} = S'S \begin{pmatrix} \gamma_2 I'_{(m\times m)} \sum_{y_{(m\times m)}} I_{(m\times m)} + \gamma_1 I'_{(m\times l_1)} \sum_{x_{(l_1\times l_1)}} I_{(l_1\times m)} \\ + (\gamma_2 - \gamma_1) I'_{(m\times l_2)} \sum_{x_{1(l_2\times l_2)}} I_{(l_2\times m)} \\ -2\gamma_1 (I'_{(m\times m)} \sum_{y_{x_{(m\times l_1)}}} I_{(l_1\times m)}) \\ -2(\gamma_1 - \gamma_2) (I'_{(m\times m)} \sum_{y_{x_{1(m\times l_2)}}} I_{(l_2\times m)}) \end{pmatrix}.$$
(3)

Upadhaya and Singh (1999) anticipated the following ratio estimator and we modify it in multivariate case,

$$t_{u} = \begin{bmatrix} t_{u1} & t_{u2} \cdots & t_{uj} \cdots & t_{um} \end{bmatrix}$$
$$t_{uj} = s_{y_{j(2)}}^{2} \prod_{k=1}^{l_{1}} \left(\frac{\overline{X}}{\frac{(1)k}{\overline{x}_{(1)k}}} \right) \prod_{k=l_{1}+1}^{l_{1}+l_{2}=l} \left(\frac{\overline{x}_{(1)k}}{\overline{x}_{(2)k}} \right), \quad j = 1, 2, ..., m, k = 1, 2, ..., l,$$
(4)

and its Var-Cov matrix is given,

$$\sum_{tu_{(m\times m)}} = S'S \begin{pmatrix} \gamma_2 I'_{(m\times m)} \sum_{y_{(m\times m)}} S_{(m\times m)} + \gamma_1 I'_{(m\times l_1)} \sum_{x_{d(l_1\times l_1)}} I_{(l_1\times m)} + (\gamma_2 - \gamma_1) I'_{(m\times l_2)} \sum_{x_{dl(l_2\times l_2)}} I_{(l_2\times m)} \\ -2\gamma_1 (I'_{(m\times m)} \sum_{y_{x_{d(m\times l_1)}}} I_{(l_1\times m)}) - 2(\gamma_1 - \gamma_2) (I'_{(m\times m)} \sum_{y_{x_{dl(m\times l_2)}}} I_{(l_2\times m)}) \end{pmatrix},$$
(5)

where I represents the identity matrix.

Das and Tripathi (1978) proposed the following ratio estimators using single auxiliary variable as,

$$t_{D1} = s_y^2 \left(\frac{\bar{X}}{\bar{x}_1}\right)^{\alpha_0}, t_{D2} = s_y^2 \left(\frac{S_x^2}{s_{x_1}^2}\right)^{\alpha_1}, t_{D3} = s_y^2 \left(\frac{\bar{X}}{\bar{X} + \alpha_2(\bar{x}_1 - \bar{X})}\right).$$

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We derived ratio type multivariate estimator following Das and Tripathi (1978) t_{D1}^{t} ,

$$t_{d} = \begin{bmatrix} t_{d1} & t_{d2} \cdots & t_{dj} \cdots & t_{d(dm)} \end{bmatrix}$$

$$t_{dj} = s_{y_{j(2)}}^{2} \prod_{k=1}^{l_{1}} \left(\frac{\overline{X}}{\frac{(1)k}{\overline{x}_{(1)k}}} \right)^{\alpha_{1}} \prod_{k=l_{1}+1}^{l_{1}+l_{2}=l} \left(\frac{\overline{x}_{(1)k}}{\overline{x}_{(2)k}} \right)^{\alpha_{2}}.$$
(6)

Its Var-Covmatrix is given,

$$\Sigma_{td_{(m\times m)}} = S'S \begin{bmatrix} \gamma_2 \sum_{y_{(m\times m)}} -\gamma_1 \sum_{yx_{d(m\times l_1)}} \sum_{y_{l_1|y_{l_1}}}^{-1} \sum_{x_{d} y_{(l_1\times m)}} \\ -(\gamma_2 - \gamma_1) \sum_{yx_{d1|(m\times l_2)}} \sum_{x_{d1|l_2|x_{l_2}}}^{-1} \sum_{x_{d1}y_{(l_2\times m)}} \end{bmatrix},$$
(7)

where α_0 is used for minimizing.

3. Proposed estimator for Variance Estimation

Adapting the estimator of Das and Tripathi (1978), given in Section (1), we develop the following variance estimator for estimating the finite population variance in the multivariate case using multi-auxiliary variables,

$$t_p = \left\lfloor t_{pj} \right\rfloor_{(1xm)},$$

where

$$t_{pj} = s_{y_{j(2)}}^{2} \left(\prod_{k=1}^{l_{1}} \left[\frac{S_{x_{k}}^{2}}{\alpha_{kj} s_{x(1)k}^{2} + (1 - \alpha_{kj}) S_{x_{k}}^{2}} \right]^{s_{kj}} \prod_{k=l_{1}+1}^{s_{kj}-l_{1}} \left[\frac{s_{x(1)k}^{2}}{\beta_{kj} s_{x(2)k}^{2} + (1 - \beta_{kj}) s_{x(1)k}^{2}} \right]^{s_{kj}^{*}} \right),$$
(8)

and g_{kj} and g_{kj}^* be the known constants which may takes the values (-1,0,1) to attain global product-type, unbiased variance and ratio-type estimators respectively, α_{kj} and β_{kj} are anonymous constants; estimated by minimizing the asymptotic Var-Cov matrix of the estimator. Up to first order of approximation, (8) may be written as in $\mathcal{E}_{i's}$,

$$t_{pj} = S_{y_j}^2 (1 + \varepsilon_{y_{j(2)}}) \left(\prod_{k=1}^{l_1} \left[\frac{1}{(1 + \alpha_{kj} \varepsilon_{x_{k(1)}})} \right]^{g_{kj}} \prod_{k=l_1+1}^{l_1+l_2=l} \left[\frac{(1 + \varepsilon_{x_{k(1)}})}{1 + \varepsilon_{x_{k(1)}} + \beta_{kj} (\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}})} \right]^{g_{kj}^*} \right), \tag{9}$$

or

$$t_{pj} = S_{y_j}^2 (1 + \varepsilon_{y_{j(2)}}) \begin{pmatrix} \prod_{k=1}^{l} \left[(1 + \alpha_{kj} \varepsilon_{x_{k(1)}})^{-1} \right]^{s_{kj}} \\ \prod_{k=l_1+1}^{l_1+l_2=l} \left[(1 + \varepsilon_{x_{k(1)}}) \left(1 + \left\{ \varepsilon_{x_{k(1)}} + \beta_{kj} (\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}}) \right\} \right)^{-1} \right]^{s_{kj}^*} \end{pmatrix}.$$

Ignoring the higher order terms and expanding up to first order estimation, we have

$$t_{pj} = S_{y_j}^2 (1 + \varepsilon_{y_{j(2)}}) \left(\prod_{k=l_1+1}^{l_1} \left[(1 - g_{kj} \alpha_{kj} \varepsilon_{k(1)}) \right] \\ \prod_{l_1+l_2=l}^{l_1+l_2=l} \left[(1 + \varepsilon_{k(1)}) \left(1 - g_{kj}^* \left\{ \varepsilon_{k(1)} + \beta_{kj} (\varepsilon_{k(2)} - \varepsilon_{k(1)}) \right\} \right) \right] \right),$$
(10)

or

$$t_{pj} = S_{y_j}^2 (1 + \varepsilon_{y_{j(2)}}) \left(1 - \sum_{k=1}^{l_1} g_{kj} \alpha_{kj} \varepsilon_{k(1)} + \sum_{k=l_1+1}^{l_1+l_2=l} g_{kj}^* \beta_{kj} \left(\varepsilon_{k(1)} - \varepsilon_{k(2)} \right) \right).$$

After some simplifications, we may get,

$$t_{pj} = S_{y_j}^2 \left(1 + \varepsilon_{y_{j(2)}} - \sum_{k=1}^{l_1} g_{kj} \alpha_{kj} \varepsilon_{k(1)} - \sum_{k=l_1+1}^{l_1+l_2=l} g_{kj}^* \beta_{kj} \left(\varepsilon_{k(2)} - \varepsilon_{k(1)} \right) \right).$$
(11)

On simplification, we may have,

$$t_{pj} = S_{y_j}^2 \begin{pmatrix} 1 + \varepsilon_{y_{j(2)}} - \sum_{k=1}^{l_1} g_{kj} \alpha_{kj} \varepsilon_{x_{k(1)}} + \sum_{k=1}^{l_1} g_{kj} \alpha_{kj}^2 \varepsilon_{x_{k(1)}}^2 + \sum_{k=1}^{l_1} g_{kj}^2 \alpha_{kj}^2 \varepsilon_{x_{k(1)}}^2 \\ + \sum_{k=l_l+1}^{l_l+l_2=l} g_{kj}^{*2} \beta_{kj}^2 (\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}})^2 - \sum_{k=l_l+1}^{l_l+l_2=l} g_{kj}^* \beta_{kj} (\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}}) \\ + \sum_{k=l_l+1}^{l_l+l_2=l} g_{kj}^* \beta_{kj}^2 (\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}})^2 + \sum_{k=l_l+1}^{l_l+l_2=l} g_{kj}^* \beta_{kj} \varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}}) \end{pmatrix}.$$
(12)

Subtracting $S_{y_j}^2$ from (12) and taking expectation we have,

$$E_{1}E_{2/l}\left(t_{pj}-S_{y_{j}}^{2}\right)=S_{y_{j}}^{2}E_{1}E_{2/l}\left(t_{pj}-S_{y_{j}}^{2}\right)=S_{y_{j$$

Since for bias (13) may be extended up to order more than one,

$$t_{pj} = S_{y_{j}}^{2} (1 + \varepsilon_{y_{j(2)}}) \begin{pmatrix} \prod_{k=l}^{l_{1}} \left[(1 - \alpha_{kj} \varepsilon_{x_{k(1)}} + \alpha_{kj}^{2} \varepsilon_{x_{k(1)}}^{2}) \right]^{s_{kj}} \\ \prod_{k=l_{1}+l_{2}=l}^{l_{1}+l_{2}=l} \left[(1 + \varepsilon_{x_{k(1)}}) \begin{pmatrix} 1 - \left\{ \varepsilon_{x_{k(1)}} + \beta_{kj} \left(\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}} \right) \right\} \\ + \left\{ \varepsilon_{x_{k(1)}} + \beta_{kj} \left(\varepsilon_{x_{k(2)}} - \varepsilon_{x_{k(1)}} \right) \right\}^{2} \end{pmatrix} \end{bmatrix}^{s_{kj}^{*}} \end{pmatrix}.$$

$$(14)$$

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After some simplification, the bias of our proposed estimator is,

$$Bias(t_{p})_{(1\times m)} = S_{y}^{2} \begin{pmatrix} \gamma_{1}A_{x_{(1\times l_{1})}} \left[g_{kj}\alpha_{kj}^{2}\right]_{(l_{1}\times m)} + \gamma_{1}A_{x_{(1\times l_{1})}} \left[g_{kj}^{2}\alpha_{kj}^{2}\right]_{(l_{1}\times m)} \\ -\gamma_{1}A_{yx_{(1\times l_{1})}} \left[g_{kj}\alpha_{kj}\right]_{(l_{1}\times m)} \\ + (\gamma_{2} - \gamma_{1})A_{yx_{1(1\times l_{2})}} \left[g_{kj}^{*}\beta_{kj}\right]_{(l_{2}\times m)} \\ + (\gamma_{2} - \gamma_{1})A_{yx_{1(1\times l_{2})}} \left[g_{kj}^{*}\beta_{kj}^{2}\right]_{(l_{2}\times m)} \\ - (\gamma_{2} - \gamma_{1})A_{yx_{1(1\times l_{2})}} \left[g_{kj}^{*2}\beta_{kj}^{2}\right]_{(l_{2}\times m)} \end{pmatrix}.$$

$$(15)$$

Using (15), we may proceed for Var-Covmatrix,

$$\sum_{t_{p(m\times m)}} = E_{1}E_{2/1} \left(\mathbf{t}_{p(bm)} - \mathbf{S}_{(bm)} \right)' \left(\mathbf{t}_{p(bm)} - \mathbf{S}_{(bm)} \right)$$

$$= S_{y}^{4}E_{1}E_{2/1} \left(\Delta_{y_{(bm)}} - \Delta_{x_{(bm)}} \overline{\boldsymbol{\sigma}}_{(n_{1}\times m)} + \Delta_{x_{1(bm)}} \omega_{(n_{2}\times m)} \right)' \left(\Delta_{y_{(bm)}} - \Delta_{x_{(bm)}} \overline{\boldsymbol{\sigma}}_{(n_{1}\times m)} + \Delta_{x_{1(bm)}} \omega_{(n_{2}\times m)} \right),$$
(16)

 $\boldsymbol{\varpi}_{_{(l_1 \times m)}} = \left[g_{kj} \alpha_{kj} \right]_{_{(l_1 \times m)}}$ and $\boldsymbol{\omega}_{_{_{(l_2 \times m)}}} = \left[g_{kj} \beta_{kj} \right]_{_{(l_2 \times m)}}$, the matrix of regression coefficients and usually these coefficients are unknown, and their estimated values are used to minimize the Var-Cov matrix of multivariate ratio type estimator. Using the results of expectations (11), (16) may be written as:

$$\Sigma_{t_{p(m\times m)}} = S'S \begin{pmatrix} \gamma_{2} \Sigma_{y_{(m\times m)}} + \gamma_{1} \overline{\sigma}'_{(m\times l_{1})} \Sigma_{x_{(l_{1}\times l_{1})}} \overline{\sigma}_{(l_{1}\times m)} - \gamma_{1} \overline{\sigma}'_{(m\times l_{1})} \Sigma_{yx_{(l_{1}\times m)}} \\ + (\gamma_{1} - \gamma_{2}) \omega'_{(l_{2}\times m)} \Sigma_{yx_{(l_{m}\times l_{2})}} + (\gamma_{1} - \gamma_{2}) \Sigma_{yx_{(l_{m}\times l_{2})}} \omega_{(l_{2}\times m)} \\ + (\gamma_{2} - \gamma_{1}) \omega'_{(m\times l_{2})} \Sigma_{x_{1}_{(l_{2}\times l_{2})}} \omega_{(l_{2}\times m)} - \gamma_{1} \Sigma_{yx_{(m\times l_{1})}} \overline{\sigma}_{(l_{1}\times m)} \end{pmatrix}.$$
(17)

We distinguish the above appearance with respect to $\overline{\sigma}$ and ω and get the optimal values as:

$$\sigma_{opt_{(l_{2}\times m)}} = \sum_{x_{(l_{2}\times l_{1})}}^{-1} \sum_{yx_{(l_{2}\times m)}} \text{ and } \omega_{opt_{(l_{2}\times m)}} = \sum_{x_{1}}^{-1} \sum_{yx_{1}}^{-1} \sum_{yx_{1}}^{-1} \cdots \sum_{yx_{n}}^{-1} \cdots \sum$$

By means of the optimum value of ϖ and ω in (17) and we may get the minimum value of Var-Cov matrix of $t_p^{t_p}$,

$${}_{\min} \sum_{t_{p(m\times m)}} = S'S \begin{pmatrix} \gamma_2 \sum_{y_{(m\times m)}} -\gamma_1 \sum_{y_{X_{(m\times l_2)}}} \sum^{-1} \sum_{x_{(l_1\times l_1)}} \sum_{y_{X_{(l_1\times m)}}} \\ -(\gamma_2 - \gamma_1) \sum_{y_{X_{1}_{(m\times l_2)}}} \sum^{-1} \sum_{x_{1_{(l_2\times l_2)}}} \sum_{y_{X_{1}_{(l_2\times m)}}} \end{pmatrix}.$$
(18)

Remark 1:

By putting $g_{kj}^* = 0$ and $g_{kj} = 0$ directly in (8), we may get the multivariate ratio type estimator for full and no information cases. Similarly, we may also get the bias and Var-Cov matrices for full and no information from (15) and (18) respectively. Remark 2:

One may get a univariate estimator based on different auxiliary variables from (8) taking j = 1 and $k = 1, 2, 3 \dots, l$ as:

$$t_{pu} = \left[t_{puj}\right]_{(1\times1)},$$

$$t_{pj} = s_{y_{1(2)}}^{2} \left(\prod_{k=1}^{l_{1}} \left[\frac{S_{x_{k}}^{2}}{\alpha_{k}s_{x(1)k}^{2} + (1-\alpha_{k})S_{x_{k}}^{2}}\right]^{s_{k}} \prod_{k=l_{1}+1}^{s_{k}} \left[\frac{s_{x(1)k}^{2}}{\beta_{k}s_{x(2)k}^{2} + (1-\beta_{k})s_{x(1)k}^{2}}\right]^{s_{k}^{*}}\right),$$

and the Var-Cov matrix for the estimator in (17) may be acquired as:

and the Var-Cov matrix for the estimator in (1/) may be acquired as

$$\Sigma_{t_{p(\mathrm{bd})}} = S'S \begin{pmatrix} \gamma_{2} \sum_{y_{(\mathrm{bd})}} + \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{x_{(l_{1}\times l_{1})}} \overline{\omega}_{(l_{1}\times l)} + (\gamma_{2} - \gamma_{1}) \omega'_{(\mathrm{l}\times l_{2})} \sum_{x_{1}} \omega_{(l_{2}\times l)} \\ -\gamma_{1} \sum_{y_{x_{(\mathrm{bd})}}} \overline{\omega}_{(l_{1}\times l)} + (\gamma_{1} - \gamma_{2}) \omega'_{(l_{2}\times l)} \sum_{y_{x_{1}}} + (\gamma_{1} - \gamma_{2}) \sum_{y_{x_{1}}} \omega_{(l_{2}\times l)} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{2}\times l)} + (\gamma_{1} - \gamma_{2}) \sum_{y_{x_{1}}} \omega_{(l_{2}\times l)} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{2}\times l)} + (\gamma_{1} - \gamma_{2}) \sum_{y_{x_{1}}} \omega_{(l_{2}\times l)} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{2}\times l)} + (\gamma_{1} - \gamma_{2}) \omega_{(l_{2}\times l)} + (\gamma_{1} - \gamma_{2}) \sum_{y_{x_{1}}} \omega_{(l_{2}\times l)} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{2}\times l_{1})} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{2}\times l_{1})} - \gamma_{1} \overline{\omega}'_{(\mathrm{l}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} - \gamma_{1} \overline{\omega}'_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} - \gamma_{1} \overline{\omega}'_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} - \gamma_{1} \overline{\omega}'_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}} \omega_{(l_{1}\times l_{1})} \sum_{y_{x_{(l_{1}\times l_{1})}}}$$

Special cases:

For some specific α , β , g and g^{*} the estimator in (9) provides some existing estimators in the following table,

Value of α, β, g and g^*	Estimators
$\alpha - 1 \alpha - 1 k \alpha^* - 0$	$t_R = s_{y_{(2)}}^2 \frac{S_x^2}{s_x^2} $ (Potio estimator)
	$S_{x}^{(2)}$ (Ratio estimator)
$\alpha = 1, g = -1 \& g^* = 0$	$t_{pr} = s_{y_{(2)}}^2 \frac{s_x^2}{S_z^2}$ (Due last estimator)
	S_x (Product estimator)
$\alpha = 1, g_{opt} \& g^* = 0$	$t_{R} = s_{y_{(2)}}^{2} \left(\frac{S_{x}^{2}}{s_{x}^{2}}\right)^{g} $ (Dec and Tripathi (1079))
	(Das and Tripathi (1978)) (Das and Tripathi (1978))

4. A Real-Life Application-Based Results and Discussion

To show the implementation of the MRCE estimator, the Canadian climate data is used as a real-life application, which is published by the National Oceanic and Atmospheric Administration (NOAA). The weather data considered for this study, is only for the month of May 2017 that are recorded on daily basis, for 37247 different weather Stations of Canada, and then the data is converted into per week information taking week as Week-1 (average temp. for May, 2017), Week-2 (average temp. for May, 2017), Week-3 (average temp. for May, 2017), Week-4 (average temp. for May, 2017). There were many stations where the required data is not recorded for full week, so such Stations are dropped, and only those weeks where the data is recorded for full week. The monthly average temperature data recorded in the last four years say, 2017, 2016, 2015, & 2013, are considered as the auxiliary variables, and for these years, such stations were dropped where temperature record is not present for full week. Finally, only 704 Stations which had the data regarding temperature for full week, are left. For this purpose, the tidyverse Package (2016) is used to detect, and eliminate missing values, and to transform other variables mutate some more functions.

Temperature averages (TAVGs) for the three weeks of May, 2017 are treated as the study variable Y_i , where i=1, 2, 3, and in the previous three years (2016, 2015 and 2013) monthly TAVGs are taken as the auxiliary variables X_i , where i=1, 2, 3.

A finite population approach is used to model the variance and covariance of weekly temperature across Canada using the data published by National Oceanic and Atmospheric Administration (NOAA), and description over the population characteristics is presented in table (A), covariance matrix is presented in table (B) and table (C) is for correlation matrix among variables in

appendix. Now, from the given population of size N = 704, a first-phase sample of size $n_1 = 211$ is selected, and necessary

calculations are made based on the first-phase sample. Using SRSWOR, another sample i.e., second-phase sample of size

 $n_2 = 105$ is selected from the already selected first-phase sample. Some necessary calculations based on second-phase sample

are also computed. The statistics computed based on the first phase, and the second-phase samples, are then incorporated into the proposed MV estimator, and the mentioned existing MV estimators for getting estimate about PV. This procedure is repeated for 1000 times. Finally, determinants for the Var-Cov matrix of each MV estimator are computed. Var-Cov matrices are computed in Table 1 for the proposed estimator, and for the altered existing estimators. The percentage relative efficiencies (PRE) of each estimator as compared to the sample variance estimator is presented using the following formula:

$$PRE = \frac{\left| \sum_{t_0} \right|}{\left| \sum_{t_*} \right|} \times 100.$$

We ruminate four study variables denoted by Y's and four auxiliary variables denoted by Xs for the multivariate situation (where, X_3 and X_4 are considered as known auxiliary; X_1 and X_2 are considered as unknown auxiliary variables). We also have shown our results for univariate situations using the same four X's as auxiliary variables. We compared our suggested estimator (t_p) with the unbiased estimator (t_0) , the Isaki (1983) estimator (t_r) , Upadhaya and Singh (1999) ratio type estimator (t_u) and Das and Tripathi (1978) ratio type estimator (t_d) .

		ce-covariance Matrix of F	res for our proposed Estin Proposed Estimator	
	\mathbf{t}_{p1}	t _{p2}	t _{p3}	\mathbf{t}_{p4}
\mathbf{t}_{p1}	0.019369890	4.905212e-03	-0.002014820	-3.803579e-03
\mathbf{t}_{p2}	0.004905212	1.653949e-02	0.001372994	-4.379532e-05
\mathbf{t}_{p3}	-0.002014820	1.372994e-03	0.010945712	5.472590e-03
\mathbf{t}_{p4}	-0.003803579	-4.379532e-05	0.005472590	2.098642e-02
	Va	riance-covariance Matrix	of \mathbf{t}_{0} Estimator	
	\mathbf{t}_{01}	t ₀₂	t ₀₃	\mathbf{t}_{04}
t ₀₁	0.07672491	0.05630260	0.04004221	0.03830438
\mathbf{t}_{02}	0.05630260	0.06388211	0.03917459	0.03796022
t ₀₃	0.04004221	0.03917459	0.04337219	0.03747599
\mathbf{t}_{04}	0.03830438	0.03796022	0.03747599	0.05273034
	Va	riance-covariance Matrix	of \mathbf{t}_{d} Estimator	
	\mathbf{t}_{d_1}	\mathbf{t}_{d_2}	\mathbf{t}_{d_3}	\mathbf{t}_{d_4}
\mathbf{t}_{d_1}	0.05563582	0.03759989	0.02706011	0.02310313
\mathbf{t}_{d_2}	0.03899938	0.04860736	0.02822920	0.02613081
\mathbf{t}_{d_3}	0.02928598	0.02923263	0.03569492	0.03007688
\mathbf{t}_{d_4}	0.02455991	0.02634051	0.02936588	0.04341882
	Va	riance-covariance Matrix	of \mathbf{t}_r Estimator	
	t _{ri}	t _{r2}	t _{r3}	t _{r4}
$\mathbf{t}_{r_{\mathrm{i}}}$	0.02253536	-0.003942296	0.04004221	0.03830438
\mathbf{t}_{r2}	0.01325979	0.025422865	0.03917459	0.03796022
\mathbf{t}_{r_3}	-0.05560742	-0.062276857	0.04337219	0.03747599
\mathbf{t}_{r_4}	-0.05750892	-0.062667890	0.03747599	0.05273034
	Var	iance-covariance Matrix o	of \mathbf{t}_{u} Estimator	
	t _{<i>u</i>1}	t _{<i>u</i>₂}	t _{<i>u</i>₃}	\mathbf{t}_{u_4}
\mathbf{t}_{u_1}	0.08124260	0.06187189	0.04004221	0.03830438
\mathbf{t}_{u_2}	0.05990383	0.06829672	0.03917459	0.03796022
t _{<i>u</i>₃}	0.04338338	0.04319781	0.04337219	0.03747599
\mathbf{t}_{u_4}	0.04250808	0.04290596	0.03747599	0.05273034
	÷			

Table 1: Variance-covariance matrices for our proposed Estimator

Table 1 shows our multivariate cases; Var-Covmatrices have been computed from (2), (4), (6), (8) and (25) to illustrate the performance of our multivariate ratio estimator. We get the (4×4) matrix and observed that the diagonal elements of each matrix show the variances for $(Y_1, ..., Y_4)$. It is also detected that the diagonal elements of our anticipated estimator have the lower variances among the other diagonal elements of existing estimators. It is noted that the estimators who are using population variance as auxiliary variable are more effective than the estimators having population mean as auxiliary variable. We can also see that our proposed and modified Isaki (1983) estimators are having lesser variances on the diagonals than Upadhaya and Singh (1999) and Das and Tripathi (1978).

Table 2: Determinant and FKE 8 of our proposed and interature estimators									
Estimator \mathbf{t}_p		\mathbf{t}_0	\mathbf{t}_r	\mathbf{t}_{d}	\mathbf{t}_{u}				
Determinants	Determinants 4.77554e-08		3.99522e-07	5.284e-07	5.4245e-06				
	PRE's for Univariate cases using four auxiliary variables								
		Weekly temperatur	e						
Estim	ator	Y1	Y2	Y3	Y4				
t)	396.10400	386.00	396.24822	251.00				
t,		137.90559	131.42477	121.508018	121.44581				
\mathbf{t}_{d}	!	340.46454	251.27817	100	100				
t _u		94.43925	93.536135	100	100				

Table 2: Determinant and PRE's of our proposed and literature estimators

Table 2 summaries the results for multivariate as well as for univariate cases. By finding the determinants of the Var-Covmatrices, we find the MSE of our proposed and literature estimators and it is observed that our anticipated estimator (\mathbf{t}_p) has the determinant 4.77554e-08 which is less than the determinant of \mathbf{t}_0 , \mathbf{t}_r , \mathbf{t}_d and \mathbf{t}_u . We also computed the numerical results by finding PRE's for every Y using the four auxiliary variables.

5. Simulation Study

The simulation study has also been computed to assess the presentation of our anticipated multivariate ratio type estimator for estimating population variance under a two-phase sampling scheme. We used a model for generating the finite populations by using the R- Statistical package. We consider four study variables (Y_1, Y_2, Y_3, Y_4) along with four auxiliary variables (X_1, X_2, X_3, X_4) for multivariate situation (where, X_3 and X_4 are considered as known auxiliary; X_1 and X_2 are considered as unknown auxiliary variables) and normal distribution is used for generating our auxiliary variables X's as:

$$X_1 \sim N(12,4), X_2 \sim N(15,3), X_3 \sim N(18,6), X_4 \sim N(16,5)$$

And the study variable is simulated as:

Model-I
$$Y_{kj} = \sum_{k=1}^{l} X + \varepsilon.$$

We generated a finite population for N = 10,000 and nominated a sample of size $n_1 = 2000$ units by SRSWOR in the firstphase and then we designated a small sample from n_1 of $n_2 = 600$ units by SRSWOR. This technique is continual q=1000 times to compute the ideals of our proposed and existing estimators.

The code for the simulation was carried out using the R statistical package (2016) and the David Robinson (2016) broom and Hadley Wickham (2016) Tidy verse packages.

		ce-covariance Matrix of P	roposed Estimator		
	\mathbf{t}_{p1}	\mathbf{t}_{p2}	\mathbf{t}_{p3}	\mathbf{t}_{p4}	
\mathbf{t}_{p1}	1.4261477	1.2066771	0.5101474	0.5941651	
\mathbf{t}_{p2}	1.2066771	1.4124647	0.4883920	0.6627137	
\mathbf{t}_{p3}	0.5101474	0.4883920	0.2882620	0.3918415	
\mathbf{t}_{p4}	0.5941651	0.6627137	0.3918415	0.5995745	
	Va	riance-covariance Matrix of	of \mathbf{t}_0 Estimator		
	t ₀₁	t ₀₂	t ₀₃	t ₀₄	
t ₀₁	1.5426375	1.3363918	0.5462599	0.6488495	
t ₀₂	1.3363918	1.6529650	0.5400216	0.7535844	
t ₀₃	0.5462599	0.5400216	0.3189577	0.4450744	
t ₀₄	0.6488495	0.7535844	0.4450744	0.7043424	
	Va	riance -covariance Matrix	of \mathbf{t}_r Estimator		
	t _{ri}	t _{r2}	t _{r3}	\mathbf{t}_{r_4}	
t _{r1}	3.733230	3.673615	1.4686897	1.986607	
\mathbf{t}_{r2}	3.673615	4.165533	1.5256706	2.188923	
t _{r3}	1.468690	1.525671	0.7053697	1.004908	
\mathbf{t}_{r_4}	1.986607	2.188923	1.0049082	1.517789	
	Va	riance-covariance Matrix of	of \mathbf{t}_{u} Estimator		
	t _{<i>u</i>1}	t _{<i>u</i>₂}	t _{<i>u</i>₃}	\mathbf{t}_{u_4}	
\mathbf{t}_{u_1}	1.6760171	1.4843051	0.6114653	0.7431973	
\mathbf{t}_{u_2}	1.4843051	1.8177848	0.6127588	0.8596508	
\mathbf{t}_{u_3}	0.6114653	0.6127588	0.3508144	0.4914471	
\mathbf{t}_{u_4}	0.7431973	0.8596508	0.4914471	0.7720322	
	Var	riance-covariance Matrix of	of \mathbf{t}_d Estimator		
	t _{d1}	t _{d2}	\mathbf{t}_{d_3}	\mathbf{t}_{d_4}	
\mathbf{t}_{d_1}	1.5840520	1.8696998	0.5453600	0.7087673	
\mathbf{t}_{d_2}	1.8696998	8.1537205	0.5015866	0.8158619	
\mathbf{t}_{d_3}	0.5453600	0.5015866	0.3312526	0.5736758	
\mathbf{t}_{d_4}	0.7087673	0.8158619	0.5736758	1.8997817	

Table 3: Variance-covariance matrix for ratio estimator

Table 3 shows our multivariate cases; Var-Covmatrices have been computed from the artificial population to observe the performance of ratio type estimator. We can see variances on the diagonals of (4×4) matrices and observe that the variance of our proposed estimator for (Y_1, Y_2, Y_3, Y_4) are less than the variances of t_0 , t_r , t_d and t_u . It shows that our planned estimator (t_p) performs better than the other existing estimators.

Estimator	t _p	\mathbf{t}_0	\mathbf{t}_r	\mathbf{t}_u	\mathbf{t}_{d}	
Determinants	0.00200573	0.0043825	0.0124250	0.0048802	1.067941	

Table 4: Determinant of our proposed and literature estimators for Model II

We compared our multivariate ratio type estimator with existing ratio type estimators. It is observed that our proposed estimator has less MSE in all univariate cases as shown in Table 5.1. In Table 5.2, our proposed estimator (\mathbf{t}_p) has lesser determinant (0.00200573, which shows the MSE for the multivariate case) among others.

6. Concluding Remarks

We proposed the multivariate ratio type estimator when some auxiliary variables are known and some are unknown. We found out the bias and the Var-Covmatrix for our proposed work. Further, we discussed the bivariate and univariate form of our proposed estimator using multi-auxiliary variables. We computed empirical results using Canadian climate data (NOAA) in Section 4. In Table 1, the Var-Covmatrices are given for our proposed estimator along with existing estimators. Table 2 demonstrated the determinants for the multivariate cases and PRE's for the univariate cases. It is observed that our proposed estimator is more effectual. We performed a simulation study in Section 5 and selected a model to check the efficiency of our proposed estimator. The usual ratio estimator behaves well when the simulation model generates symmetric error distributions and linear associations between the auxiliary variables and the outcome. We used the normal distribution for generating our four auxiliary variables and simulated the data for 1000 times. In Table 3 and Table 4, it is shown that our proposed estimator \mathbf{t}_p is more efficient than unbiased variance estimator (\mathbf{t}_0) , Isaki (1983) (\mathbf{t}_0) , Upadhaya and Singh (1999) (\mathbf{t}_u) and Das and

Tripathi (1978) (\mathbf{t}_d) and we gained the lesser MSE for univariate cases. In future, we hope to discuss the effects of covariance terms in formation of a variance-covariance matrix. We also want to propose this work under stratified sampling.

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Population	NOAA
Y_1	Week-1 (average temp. for May, 2017)
<i>Y</i> ₂	Week-2 (average temp. for May, 2017)
<i>Y</i> ₃	Week-3 (average temp. for May, 2017)
Y_4	Week-4 (average temp. for May, 2017)
X_1	Year-2016 (average temp. for May)
X_2	Year-2015 (average temp. for May)
<i>X</i> ₃	Year-2014 (average temp. for May)
X_4	Year-2013 (average temp. for May)

Appendix Table A: Details of Variables for Population

Table B: Covariance and Correlation

Population	Y_1	Y_2	Y_3	Y_4	X_1	X_{2}	X_3	X_4
Y_1	16.4344	11.7119	11.8797	11.2634	5.0995	2.0234	5.6778	0.5231
<i>Y</i> ₂	11.7119	10.0879	9.3665	9.8238	1.3889	2.5090	5.0955	0.7491
<i>Y</i> ₃	11.8797	9.3666	9.7386	9.3817	2.8759	2.5086	3.8010	1.3053
Y_4	11.2634	9.8238	9.3817	9.7610	1.3933	3.0050	4.4580	0.9370
X_1	5.0996	1.3888	2.8759	1.3933	7.4839	0.0406	-0.0779	-0.0538
X_2	2.0234	2.5090	2.5086	3.0050	0.0406	4.6808	-0.0304	0.0080
<i>X</i> ₃	5.6777	5.0955	3.8009	4.4571	-0.0779	-0.0304	6.6511	-0.0093
X_4	0.5231	0.7490	1.3052	0.9369	-0.0538	0.0080	-0.0093	2.0420

 Y_1 Y_2 Y_3 Y_4 X_1 X_2 X_3 X_4 Population Y_1 1.0000 0.8869 0.7494 0.7654 0.9026 0.8528 0.8650 0.9122 Y_2 0.7789 0.8513 0.8869 1.0000 0.7215 0.7535 0.8397 0.8273 Y_3 0.7494 0.7215 1.0000 0.7959 0.7917 0.8342 0.7632 0.8683 Y_4 0.7654 0.7535 0.7959 1.00000.8335 0.8118 0.8301 0.8193 X_1 0.9453 0.7917 0.9561 0.9026 0.8397 0.8335 1.0000 0.9420 X_2 0.8528 0.7789 0.8683 0.8118 0.9420 1.00000.9667 0.9208 X_3 0.86500.8273 0.8342 0.8301 0.9561 0.9667 1.00000.9257 X_4 0.9453 0.9122 0.8513 0.7632 0.8193 0.9208 0.9257 1.0000

Table C: Correlation Matrix